## Satisfiability Modulo Theories

Clark Barrett, Stanford University
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Disclamer: The literature on SMT and its applications is vast. The bibliographic references provided here are just a sample. Apologies to all authors whose work is not cited.

## Introduction

## A (Very) Brief History of Automated Reasoning

Philosophers have long dreamed of machines that can reason. The pursuit of this dream has occupied some of the best minds and led both to great acheivements and great disappointments.


## Automated Reasoning

## Automated Reasoning: A Failure?

- At the turn of the century, automated reasoning was still considered by many to be impractical for most real-world applications
- Interesting problems appeared to be beyond the reach of automated methods because of decidability and complexity barriers
- The dream of Hilbert's mechanized mathematics or Leibniz's calculating machine was believed by many to be simply unattainable


## The Satisfiability Revolution

## Princeton, c. 2000

- Chaff SAT solver: orders of magnitude faster than previous SAT solvers
- Important observation: many real-world problems do not exhibit worst-case theoretical performance

Palo Alto, c. 2001

- Idea: combine fast new SAT solvers with decision procedures for decidable first-order theories
- SVC, CVC solvers (Stanford); ICS, Yices solvers (SRI)
- Satisfiability Modulo Theories (SMT) was born


## SMT solvers

SMT solvers: general-purpose logic engines

- Given condition $X$, is it possible for $Y$ to happen
- $X$ and $Y$ are expressed in a rich logical language
- First-order logic
- Domain-specific reasoning
- arithmetic, arrays, bit-vectors, data types, etc.

SMT solvers are changing the way people solve problems

- Instead of building a special-purpose solver - Translate into a logical formula and use an SM ${ }^{\text {T}}$ solver
- Not only easier, often better


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Theory Solvers

## Theory Solvers

Given a theory $T$, a Theory Solver for $T$ takes as input a set $\Phi$ of literals and determines whether $\Phi$ is $T$-satisfiable.
$\Phi$ is $T$-satisfiable iff there is some model $M$ of $T$ such that each formula in $\Phi$ holds in $M$.

## Theories of Interest: UF

Equality ( $=$ ) with Uninterpreted Functions [NO80, BD94, NO07]
Typically used to abstract unsupported constructs, e.g.:

- non-linear multiplication in arithmetic
- ALUs in circuits

Example: The formula

$$
a *(|b|+c)=d \wedge b *(|a|+c) \neq d \wedge \quad a=b
$$

is unsatisfiable, but no arithmetic reasoning is needed:
if we abstract it to

$$
\operatorname{mul}(a, \operatorname{add}(a b s(b), c))=d \wedge \operatorname{mul}(b, \operatorname{add}(a b s(a), c)) \neq d \wedge a=b
$$

it is still unsatisfiable

## Theories of Interest: Arithmetic

Very useful, for obvious reasons

Restricted fragments (over the reals or the integers) support more efficient methods:

- Bounds: $x \bowtie k$ with $\bowtie \in\{<,>, \leqslant, \geqslant,=\}\left[\right.$ BBC $\left.^{+} 05 \mathrm{a}\right]$
- Difference logic: $x-y \bowtie k$, with $\bowtie \in\{<,>, \leqslant, \geqslant,=\}$ [NO05, WIGG05, CM06]
- UTVPI: $\pm x \pm y \bowtie k$, with $\bowtie \in\{<,>, \leqslant, \geqslant,=\}$ [LM05]
- Linear arithmetic, e.g: $2 x-3 y+4 z \leqslant 5$ [DdM06]
- Non-linear arithmetic, e.g:

$$
2 x y+4 x z^{2}-5 y \leqslant 10\left[\mathrm{BLNM}^{+} 09, \mathrm{ZM} 10, \mathrm{JdM} 12\right]
$$

## Theories of Interest: Arrays

Used in software verification and hardware verification (for memories) [SBDL01, $\mathrm{BNO}^{+} 08 \mathrm{a}$, dMB09]

Two interpreted function symbols read and write
Axiomatized by:

- $\forall a \forall i \forall v \cdot \operatorname{read}(\operatorname{write}(a, i, v), i)=v$
- $\forall a \forall i \forall j \forall v . i \neq j \rightarrow \operatorname{read}(\operatorname{write}(a, i, v), j)=\operatorname{read}(a, j)$

Sometimes also with extensionality:

- $\forall a \forall b$. $(\forall i \cdot \operatorname{read}(a, i)=\operatorname{read}(b, i) \rightarrow a=b)$

Is the following set of literals satisfiable in this theory?

$$
\operatorname{write}(a, i, x) \neq b, \operatorname{read}(b, i)=y, \operatorname{read}(\operatorname{write}(b, i, x), j)=y, a=b, i=j
$$

## Theories of Interest: Bitvectors

Useful both in hardware and software verification $\left[\mathrm{BCF}^{+} 07, \mathrm{BB} 09, \mathrm{HBJ}^{+}\right.$14]

Universe consists of (fixed-sized) vectors of bits

Different types of operations:

- String-like: concat, extract, ...
- Logical: bit-wise not, or, and, ...
- Arithmetic: add, subtract, multiply, ...
- Comparison: $<,>, \ldots$

Is this formula satisfiable over bitvectors of size 3?

$$
a[1: 0] \neq b[1: 0] \wedge(a \mid b)=c \wedge c[0]=0 \wedge a[1]+b[1]=0
$$

## Implementing a Theory Solver: Difference Logic

We consider a simple example: difference logic.
In difference logic, we are interested in the satisfiability of a conjunction of arithmetic atoms.

Each atom is of the form $x-y \bowtie c$, where $x$ and $y$ are variables, $c$ is a numeric constant, and $\bowtie \in\{=,<, \leqslant,>, \geqslant\}$.

The variables can range over either the integers (QF_IDL) or the reals (QF_RDL).

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- $x-y<c \quad \Longrightarrow \quad x-y \leqslant c-1$ (integers)


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- $x-y>c \quad \Longrightarrow \quad y-x<-c$
- $x-y<c \quad \Longrightarrow \quad x-y \leqslant c-1$ (integers)
- $x-y<c \quad \Longrightarrow \quad x-y \leqslant c-\delta$ (reals)


## Difference Logic

Now we have a conjunction of literals, all of the form $x-y \leqslant c$.

From these literals, we form a weighted directed graph with a vertex for each variable.

For each literal $x-y \leqslant c$, there is an edge $x \xrightarrow{c} y$.

The set of literals is satisfiable iff there is no cycle for which the sum of the weights on the edges is negative.

There are a number of efficient algorithms for detecting negative cycles in graphs.

## Difference Logic Example

$$
x-y=5 \wedge z-y \geqslant 2 \wedge z-x>2 \wedge w-x=2 \wedge z-w<0
$$

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\begin{aligned}
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& z-w<0
\end{aligned}
$$

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\begin{aligned}
& x-y=5 \\
& z-y \geqslant 2 \\
& z-x>2 \quad \Rightarrow \\
& w-x=2 \\
& z-w<0
\end{aligned}
$$

## Difference Logic Example

$$
x-y=5 \wedge z-y \geqslant 2 \wedge z-x>2 \wedge w-x=2 \wedge z-w<0
$$

$$
\begin{array}{ll}
x-y=5 \\
z-y \geqslant 2 \\
z-x>2 \\
w-x=2 \\
z-w<0 & \Rightarrow \\
y-y \leqslant 5 \wedge y-x \leqslant-5 \\
& x-z \leqslant-2 \\
& z-x \leqslant 2 \wedge x-w \leqslant-2 \\
z-w \leqslant-1
\end{array}
$$

## Difference Logic Example



## DPLL(T): Combining $T$-Solvers with SAT

## Satisfiability Modulo a Theory $T$

Def. A formula is (un)satisfiable in a theory $T$, or $T$-(un)satisfiable, if there is a (no) model of $T$ that satisfies it

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## Lifting SAT Technology to SMT

Two main approaches:

1. "Eager" [PRSS99, SSB02, SLB03, BGV01, BV02]

- translate into an equisatisfiable propositional formula
- feed it to any SAT solver

Notable systems: UCLID

- abstract the input formula to a propositional one
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- use a theory decision procedure to refine the formula and guide
+h- CAT NO1…

Notable systems: cvc5, z3

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2. "Lazy" [ACG00, dMR02, BDS02, ABC ${ }^{+} 02$ ]

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## Lazy Approach - Main Benefits

- Every tool does what it is good at:
- SAT solver takes care of Boolean information
- Theory solver takes care of theory information
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- Modular approach:
- SAT and theory solvers communicate via a simple API [GHN+04]
- SMT for a new theory only requires new theory solver


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system with few new lines of code (tens)


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## An Abstract Framework for Lazy SMT

Several variants and enhancements of lazy SMT solvers exist

They can be modeled abstractly and declaratively as transition systems

A transition system is a binary relation over states, induced by a set of conditional transition rules

The framework can be first developed for SAT and then extended to lazy SMT [NOT06, KG07]

## The Original DPLL Procedure

- Modern SAT solvers are based on the DPLL procedure [DP60, DLL62]
- DPLL tries to build incrementally a satisfying truth assignment $M$ for a CNF formula $F$
- $M$ is grown by
- deducing the truth value of a literal from $M$ and $F$, or
- guessing a truth value
- If a wrong guess for a literal leads to an inconsistency, the procedure backtracks and tries the opposite value


## An Abstract Framework for DPLL

States:

$$
\text { fail or }\langle M, F\rangle
$$

where

- $M$ is a sequence of literals and decision points • denoting a partial truth assignment
- $F$ is a set of clauses denoting a CNF formula

Def. If $M=M_{0} \bullet M_{1} \bullet \cdots \bullet M_{n}$ where each $M_{i}$ contains no decision points

- $M_{i}$ is decision level $i$ of $M$
- $M^{[i]} \stackrel{\text { def }}{=} M_{0} \bullet \cdots \bullet M_{i}$


## An Abstract Framework for DPLL

States:

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Initial state:

- $\left\langle(), F_{0}\right\rangle$, where $F_{0}$ is to be checked for satisfiability

Expected final states:

- fail if $F_{0}$ is unsatisfiable
- $\langle M, G\rangle$ otherwise, where
- $G$ is equivalent to $F_{0}$ and
- $M$ satisfies $G$


## Transition Rules: Notation

States treated like records:

- M denotes the truth assignment component of current state
- F denotes the formula component of current state

Transition rules in guarded assignment form [KG07]

| $p_{1} \quad \cdots$ | $p_{n}$ |
| :---: | :---: | :---: |
| $\left[\mathrm{M}:=e_{1}\right] \quad\left[\mathrm{F}:=e_{2}\right]$ |  |

updating $\mathrm{M}, \mathrm{F}$ or both when premises $p_{1}, \ldots, p_{n}$ all hold

## Transition Rules for the Original DPLL

Extending the assignment

Propagate $\frac{l_{1} \vee \cdots \vee l_{n} \vee l \in \mathrm{~F} \quad \bar{l}_{1}, \ldots, \bar{l}_{n} \in \mathrm{M} \quad l, \bar{l} \notin \mathrm{M}}{\mathrm{M}:=\mathrm{M} l}$

Note: When convenient, treat M as a set
Note: Clauses are treated modulo ACI of $\vee$

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Decide $\frac{l \in \operatorname{Lit}(\mathrm{~F}) \quad l, \bar{l} \notin \mathrm{M}}{\mathrm{M}:=\mathrm{M} \bullet l}$

Note: $\operatorname{Lit}(F) \stackrel{\text { def }}{=}\{l \mid l$ literal of $F\} \cup\{\bar{l} \mid l$ literal of $F\}$

## Transition Rules for the Original DPLL

Repairing the assignment

Fail $\frac{l_{1} \vee \cdots \vee l_{n} \in \mathrm{~F} \quad \bar{l}_{1}, \ldots, \bar{l}_{n} \in \mathrm{M} \quad \bullet \notin \mathrm{M}}{\text { fail }}$

Note: Last premise of Backtrack enforces chronological backtracking

## Transition Rules for the Original DPLL

Repairing the assignment

$$
\text { Fail } \frac{l_{1} \vee \cdots \vee l_{n} \in \mathrm{~F} \quad \bar{l}_{1}, \ldots, \bar{l}_{n} \in \mathrm{M} \quad \bullet \notin \mathrm{M}}{\text { fail }}
$$

## Backtrack

$$
\begin{gathered}
l_{1} \vee \cdots \vee l_{n} \in \mathrm{~F} \quad \bar{l}_{1}, \ldots, \bar{l}_{n} \in \mathrm{M} \quad \mathrm{M}=M \bullet l N \quad \bullet \notin N \\
\mathrm{M}:=M \bar{l}
\end{gathered}
$$

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## From DPLL to CDCL Solvers (1)

To model conflict-driven backjumping and learning, add to states a third component C whose value is either no or a conflict clause

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States: fail or $\langle M, F, C\rangle$
Initial state:

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## From DPLL to CDCL Solvers (2)

Replace Backtrack with

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Replace Backtrack with
Conflict $\frac{C=\text { no } \quad l_{1} \vee \cdots \vee l_{n} \in \mathrm{~F} \quad \bar{l}_{1}, \ldots, \bar{l}_{n} \in \mathrm{M}}{\mathrm{C}:=l_{1} \vee \cdots \vee l_{n}}$
$\operatorname{Explain} \frac{C=l \vee D \quad l_{1} \vee \cdots \vee l_{n} \vee \bar{l} \in \mathrm{~F} \quad \bar{l}_{1}, \ldots, \bar{l}_{n}<_{\mathrm{M}} \bar{l}}{\mathrm{C}:=l_{1} \vee \cdots \vee l_{n} \vee D}$

Backjump $\frac{\mathrm{C}=l_{1} \vee \cdots \vee l_{n} \vee l \text { lev } \bar{l}_{1}, \ldots, \operatorname{lev} \bar{l}_{n} \leqslant i<\operatorname{lev} \bar{l}}{\mathrm{C}:=\text { no } \mathrm{M}:=\mathrm{M}^{[i]} l}$

Note: $l<_{\mathrm{M}} l^{\prime}$ if $l$ occurs before $l^{\prime}$ in M
lev $l=i$ iff $l$ occurs in decision level $i$ of M

## From DPLL to CDCL Solvers (2)

Replace Backtrack with
Conflict $\frac{\mathrm{C}=\text { no } \quad l_{1} \vee \cdots \vee l_{n} \in \mathrm{~F} \quad \bar{l}_{1}, \ldots, \bar{l}_{n} \in \mathrm{M}}{\mathrm{C}:=l_{1} \vee \cdots \vee l_{n}}$

Explain $\frac{C=l \vee D \quad l_{1} \vee \cdots \vee l_{n} \vee \bar{l} \in \mathrm{~F} \quad \bar{l}_{1}, \ldots, \bar{l}_{n}<_{\mathrm{M}} \bar{l}}{\mathrm{C}:=l_{1} \vee \cdots \vee l_{n} \vee D}$

Backjump

$$
\begin{gathered}
\mathrm{C}=l_{1} \vee \cdots \vee l_{n} \vee l \quad \operatorname{lev} \bar{l}_{1}, \ldots, \operatorname{lev} \bar{l}_{n} \leqslant i<\operatorname{lev} \bar{l} \\
\mathrm{C}:=\text { no } \mathrm{M}:=\mathrm{M}^{[i]} l
\end{gathered}
$$

Maintain invariant: $\mathrm{F} \models_{\mathrm{p}} \mathrm{C}$ and $\mathrm{M} \models_{\mathrm{p}} \neg \mathrm{C}$ when $\mathrm{C} \neq$ no
Note: $\models_{\mathrm{p}}$ denotes propositional entailment

## From DPLL to CDCL Solvers (3)

Modify Fail to

## From DPLL to CDCL Solvers (3)

Modify Fail to
Fail $\frac{C \neq \text { no } \bullet \notin M}{\text { fail }}$

## Execution Example

$$
F:=\{1, \overline{1} \vee 2, \overline{3} \vee 4, \overline{5} \vee \overline{6}, \overline{1} \vee \overline{5} \vee 7, \overline{2} \vee \overline{5} \vee 6 \vee \overline{7}\}
$$

| M | F | C | rule |
| :---: | :---: | :---: | :---: |
|  | $F$ | no |  |

## Execution Example

$$
F:=\{1, \overline{1} \vee 2, \overline{3} \vee 4, \overline{5} \vee \overline{6}, \overline{1} \vee \overline{5} \vee 7, \overline{2} \vee \overline{5} \vee 6 \vee \overline{7}\}
$$

| M | F | C | rule |
| :---: | :---: | :---: | :---: | :--- |
|  | $F$ | no |  |
| 1 | $F$ | no | by Propagate |

## Execution Example

$$
F:=\{1, \overline{1} \vee 2, \overline{3} \vee 4, \overline{5} \vee \overline{6}, \overline{1} \vee \overline{5} \vee 7, \overline{2} \vee \overline{5} \vee 6 \vee \overline{7}\}
$$

| M | F | C | rule |
| :--- | :--- | :--- | :--- |
|  | $F$ | no |  |
| 1 | $F$ | no | by Propagate |
| 12 | $F$ | no | by Propagate |

## Execution Example

$$
F:=\{1, \overline{1} \vee 2, \overline{3} \vee 4, \overline{5} \vee \overline{6}, \overline{1} \vee \overline{5} \vee 7, \overline{2} \vee \overline{5} \vee 6 \vee \overline{7}\}
$$

| M | F | C | rule |
| ---: | ---: | :--- | :--- |
|  | $F$ | no |  |
| 1 | $F$ | no | by Propagate |
| 12 | $F$ | no | by Propagate |
| $12 \bullet 3$ | $F$ | no | by Decide |

## Execution Example

| M | F | C | rule |
| :---: | :---: | :---: | :---: |
|  | $F$ | no |  |
| 1 | $F$ | no | by Propagate |
| 12 | $F$ | no | by Propagate |
| $12 \cdot 3$ | $F$ | no | by Decide |
| $12 \cdot 34$ | $F$ | no | by Propagate |

## Execution Example



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| M | F | C | rule |
| :---: | :---: | :---: | :---: |
|  | $F$ | no |  |
| 1 | $F$ | no | by Propagate |
| 12 | $F$ | no | by Propagate |
| $12 \cdot 3$ | $F$ | no | by Decide |
| $12 \cdot 34$ | $F$ | no | by Propagate |
| $12 \cdot 34 \cdot 5$ | $F$ | no | by Decide |
| $12 \cdot 34 \bullet 5 \overline{6}$ | $F$ | no | by Propagate |

## Execution Example

| M | F | C | rule |
| :---: | :---: | :---: | :---: |
|  | $F$ | no |  |
| 1 | $F$ | no | by Propagate |
| 12 | $F$ | no | by Propagate |
| $12 \cdot 3$ | $F$ | no | by Decide |
| $12 \cdot 34$ | $F$ | no | by Propagate |
| $12 \cdot 34 \cdot 5$ | $F$ | no | by Decide |
| $12 \cdot 34 \cdot 5 \overline{6}$ | $F$ | no | by Propagate |
| $12 \cdot 34 \cdot 5 \overline{6} 7$ | F | no | by Propagate |

## Execution Example

| M | F | c | rule |
| :---: | :---: | :---: | :---: |
|  | $F$ | no |  |
| 1 | F | no | by Propagate |
| 12 | F | no | by Propagate |
| $12 \cdot 3$ | F | no | by Decide |
| $12 \cdot 34$ | F | no | by Propagate |
| $12 \cdot 34 \bullet 5$ | $\stackrel{F}{F}$ | no | by Decide |
| $12034 \bullet 56$ $12 \cdot 34 \cdot 567$ | $\stackrel{F}{F}$ | no | by Propagate by Propagate |
| $12 \bullet 34 \cdot 567$ | F | $\overline{2} \vee \overline{5} \vee 6 \vee \overline{7}$ | by Conflict |

## Execution Example

|  |  |  |  |
| :---: | :---: | :---: | :---: |
|  | $F$ | no |  |
| 1 | $F$ | no | by Propagate |
| 12 | $F$ | no | by Propagate |
| $12 \cdot 3$ | $F$ | no | by Decide |
| $12 \cdot 34$ | $F$ | no | by Propagate |
| $12 \cdot 34 \cdot 5$ | $F$ | no | by Decide |
| $12 \cdot 34 \cdot 5 \overline{6}$ | $F$ | no | by Propagate |
| $12 \cdot 34 \bullet 5 \underline{\overline{6}} 7$ | $F$ | no | by Propagate |
| $12 \cdot 34 \bullet 5 \overline{6} 7$ | F | $\overline{2} \vee \overline{5} \vee 6 \vee \overline{7}$ | by Conflict |
| $12 \cdot 34 \cdot 5 \overline{6} 7$ | $F$ | $\overline{1} \vee \overline{2} \vee \overline{5} \vee 6$ | by Explain with $\overline{1} \vee \overline{5} \vee 7$ |

## Execution Example

| $F:=\{1, \overline{1} \vee 2, \overline{3} \vee 4, \overline{5}$M F C rule |  |  |  |
| :---: | :---: | :---: | :---: |
|  | $F$ | no |  |
| 1 | F | no | by Propagate |
| 12 | F | no | by Propagate |
| $12 \cdot 3$ | $F$ | no | by Decide |
| $12 \cdot 34$ | F | no | by Propagate |
| $12 \cdot 34 \cdot 5$ | $F$ | no | by Decide |
| $12 \cdot 34 \cdot 5 \overline{6}$ | $F$ | no | by Propagate |
| $12 \cdot 34 \cdot 5 \underline{6} 7$ | $F$ | no | by Propagate |
| $12 \cdot 34 \cdot 5 \underline{6} 7$ | $F$ | $\underline{\overline{2}} \vee \overline{5} \vee \underline{6} \vee \overline{7}$ | by Conflict |
| $12 \cdot 34 \cdot 5 \overline{6} 7$ | $F$ | $\overline{1} \vee \overline{2} \vee \overline{5} \vee 6$ | by Explain with $\overline{1} \vee \overline{5} \vee 7$ |
| $12 \cdot 34 \cdot 5 \overline{6} 7$ | $F$ | $\overline{1} \vee \overline{2} \vee \overline{5}$ | by Explain with $\overline{5} \vee \overline{6}$ |

## Execution Example



## Execution Example

| M | F | C | rule |
| :---: | :---: | :---: | :---: |
|  | $F$ | no |  |
| 1 | $F$ | no | by Propagate |
| 12 | $F$ | no | by Propagate |
| $12 \cdot 3$ | $F$ | no | by Decide |
| $12 \cdot 34$ | $F$ | no | by Propagate |
| $12 \cdot 34 \cdot 5$ | $F$ | no | by Decide |
| $12 \cdot 34 \cdot 5 \frac{5}{6}$ | $F$ | no | by Propagate |
| $12 \cdot 34 \cdot 5 \underline{6} 7$ | $F$ | no | by Propagate |
| $12 \cdot 34 \cdot 5 \overline{6} 7$ | $F$ | $\underline{\overline{2}} \vee \frac{\overline{5}}{} \vee \underline{6} \vee \overline{7}$ | by Conflict - |
| $12 \cdot 34 \cdot 5 \overline{6} 7$ | $F$ | $\overline{1} \vee \overline{2} \vee \overline{5} \vee \frac{5}{5}$ | by Explain with $\frac{\overline{1}}{5} \vee \overline{5} \vee 7$ |
| $12 \cdot 34 \cdot 5 \overline{6} \frac{7}{5}$ | $F$ | $\overline{1} \vee \overline{2} \vee \overline{5}$ | by Explain with $\overline{5} \vee \overline{6}$ |
| $12 \overline{5}$ | $F$ | no | by Backjump |
| $12 \overline{5} \cdot 3$ | $F$ | no | by Decide |

## From DPLL to CDCL Solvers (4)

Also add

Learn $\stackrel{\mathrm{F} \models_{\mathrm{p}} C \quad C \notin \mathrm{~F}}{\mathrm{~F}: \mathrm{F}}$

$$
\mathrm{F}:=\mathrm{F} \cup\{C\}
$$

Forget $\frac{\mathrm{C}=\mathrm{no} \quad \mathrm{F}=G \cup\{C\} \quad G \models_{\mathrm{p}} C}{\mathrm{~F}:=G}$

Restart

$$
\mathrm{M}:=\mathrm{M}^{[0]} \quad \mathrm{C}:=\mathrm{no}
$$

Note: Learn can be applied to any clause stored in $C$ when $C \neq$ no

## From SAT to SMT

Same states and transitions but

- F contains quantifier-free clauses in some theory $T$
- $M$ is a sequence of theory literals and decision points
- the DPLL system is augmented with rules $T$-Conflict, $T$-Propagate, $T$-Explain
- maintains invariant: $\mathrm{F} \models_{T} \mathrm{C}$ and $\mathrm{M} \models_{\mathrm{p}} \neg \mathrm{C}$ when $\mathrm{C} \neq$ no

Def. $F \models_{T} G$ iff every model of $T$ that satisfies $F$ satisfies $G$ as well

## SMT-level Rules

Fix a theory $T$
$T$-Conflict $\frac{\mathrm{C}=\text { no } \quad l_{1}, \ldots, l_{n} \in \mathrm{M} \quad l_{1}, \ldots, l_{n} \models_{T} \perp}{\mathrm{C}:=\bar{l}_{1} \vee \cdots \vee \bar{l}_{n}}$

## SMT-level Rules

Fix a theory $T$
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$T$-Propagate $\frac{l \in \operatorname{Lit}(\mathrm{~F}) \quad \mathrm{M} \models_{T} l \quad l, \bar{l} \notin \mathrm{M}}{\mathrm{M}:=\mathrm{M} l}$

## SMT-level Rules

Fix a theory $T$
$T$-Conflict $\frac{\mathrm{C}=\text { no } \quad l_{1}, \ldots, l_{n} \in \mathrm{M} \quad l_{1}, \ldots, l_{n} \models_{T} \perp}{\mathrm{C}:=\bar{l}_{1} \vee \cdots \vee \bar{l}_{n}}$
$T$-Propagate $\frac{l \in \operatorname{Lit}(\mathrm{~F}) \mathrm{M} \models_{T} l \quad l, \bar{l} \notin \mathrm{M}}{\mathrm{M}:=\mathrm{M} l}$
$T$-Explain $\frac{\mathrm{C}=l \vee D \quad \bar{l}_{1}, \ldots, \bar{l}_{n} \models_{T} \bar{l} \quad \bar{l}_{1}, \ldots, \bar{l}_{n}<_{\mathrm{M}} \bar{l}}{\mathrm{C}:=l_{1} \vee \cdots \vee l_{n} \vee D}$

Note: $\perp=$ empty clause
Note: $\models_{T}$ decided by theory solver

## Modeling a Very Lazy Theory Approach

$$
\underbrace{g(a)=c}_{1} \wedge \underbrace{f(g(a)) \neq f(c)}_{\overline{2}} \vee \underbrace{g(a)=d}_{3} \wedge \underbrace{c \neq d}_{\overline{4}}
$$

## Modeling a Very Lazy Theory Approach

$$
\begin{aligned}
& \underbrace{g(a)=c}_{1} \wedge \underbrace{f(g(a)) \neq f(c)}_{\overline{2}} \vee \underbrace{g(a)=d}_{3} \wedge \underbrace{c \neq d}_{\overline{4}} \\
& \text { M F } \\
& 1, \overline{2} \vee 3, \overline{4} \\
& \text { C rule }
\end{aligned}
$$

## Modeling a Very Lazy Theory Approach

$$
\begin{gathered}
\underbrace{g(a)=c}_{1} \wedge \underbrace{f(g(a)) \neq f(c)}_{\overline{2}} \vee \underbrace{g(a)=d}_{3} \wedge \underbrace{c \neq d}_{\overline{4}} \\
\begin{array}{cc}
\text { M F } & \text { C rule }
\end{array} \\
\begin{array}{l}
1, \overline{2} \vee 3, \overline{4} \\
1 \overline{4} \quad 1, \overline{2} \vee 3, \overline{4}
\end{array} \begin{array}{c}
\text { no } \\
\text { no }
\end{array} \quad \text { by Propagate }{ }^{+}
\end{gathered}
$$

## Modeling a Very Lazy Theory Approach

$$
\underbrace{g(a)=c}_{1} \wedge \underbrace{f(g(a)) \neq f(c)}_{\overline{2}} \vee \underbrace{g(a)=d}_{3} \wedge \underbrace{c \neq d}_{\overline{4}}
$$

| M | F | C | rule |
| ---: | :--- | :--- | :--- |
| $\overline{\overline{4}} \quad 1, \overline{2} \vee 3, \overline{4}$ | no |  |  |
|  | no | by Propagate $^{+}$ |  |
|  | no | by Decide |  |

## Modeling a Very Lazy Theory Approach

$$
\underbrace{g(a)=c}_{1} \wedge \underbrace{f(g(a)) \neq f(c)}_{\overline{2}} \vee \underbrace{g(a)=d}_{3} \wedge \underbrace{c \neq d}_{\overline{4}}
$$

| M | F | C | rule |
| ---: | :--- | :---: | :--- |
|  | $1, \overline{2} \vee 3, \overline{4}$ | no |  |
| $1 \overline{\overline{4}} \quad 1, \overline{2} \vee 3, \overline{4}$ | no | by Propagate ${ }^{+}$ |  |
| $1 \overline{4} \cdot \frac{\overline{2}}{4} \cdot \overline{2}$ | $1, \overline{2} \vee 3, \overline{4}$ | no | by Decide |
| $1, \overline{2} \vee 3, \overline{4}$ | $\overline{1} \vee 2 \vee 4$ | by $T$-Conflict |  |

## Modeling a Very Lazy Theory Approach

$$
\underbrace{g(a)=c}_{1} \wedge \underbrace{f(g(a)) \neq f(c)}_{\overline{2}} \vee \underbrace{g(a)=d}_{3} \wedge \underbrace{c \neq d}_{\overline{4}}
$$

| M | F | C | rule |
| :---: | :---: | :---: | :---: |
|  | 1, $\overline{2} \vee 3, \overline{4}$ | no |  |
| $1 \overline{4}$ | $1, \overline{2} \vee 3, \overline{4}$ | no | by Propagate ${ }^{+}$ |
| $1 \overline{4} \cdot \overline{2}$ | $1, \overline{2} \vee 3, \overline{4}$ | no | by Decide |
| $1 \underline{4} \cdot \underline{2}$ | $1, \overline{2} \vee 3, \underline{4}$ | $\overline{1} \vee 2 \vee 4$ | by $T$-Conflict |
| $1 \overline{4} \cdot \overline{2}$ | $1, \overline{2} \vee 3, \overline{4}, \overline{1} \vee 2 \vee 4$ | $\overline{1} \vee 2 \vee 4$ | by Learn |

## Modeling a Very Lazy Theory Approach

$$
\underbrace{g(a)=c}_{1} \wedge \underbrace{f(g(a)) \neq f(c)}_{\overline{2}} \vee \underbrace{g(a)=d}_{3} \wedge \underbrace{c \neq d}_{\overline{4}}
$$

| M | F | C | rule |
| ---: | :--- | :---: | :--- |
|  | $1, \overline{2} \vee 3, \overline{4}$ | no |  |
| $1 \overline{4} \overline{4}$ | $1, \overline{2} \vee 3, \overline{4}$ | no | by Propagate ${ }^{+}$ |
| $1 \overline{4} \bullet \overline{2}$ | $1, \overline{2} \vee 3, \overline{4}$ | no | by Decide |
| $1 \overline{4} \bullet \overline{2}$ | $1, \overline{2} \vee 3, \overline{4}$ | $\overline{1} \vee 2 \vee 4$ | by $T$-Conflict |
| $1 \overline{4} \bullet \frac{\overline{2}}{2}$ | $1, \overline{2} \vee 3, \overline{4}, \overline{1} \vee 2 \vee 4$ | $\overline{1} \vee 2 \vee 4$ | by Learn |
| $1 \overline{4}$ | $1, \overline{2} \vee 3, \overline{4}, \overline{1} \vee 2 \vee 4$ | no | by Restart |

## Modeling a Very Lazy Theory Approach

$$
\underbrace{g(a)=c}_{1} \wedge \underbrace{f(g(a)) \neq f(c)}_{\overline{2}} \vee \underbrace{g(a)=d}_{3} \wedge \underbrace{c \neq d}_{\overline{4}}
$$

| M | F | C | rule |
| :---: | :---: | :---: | :---: |
|  | $1, \overline{2} \vee 3, \overline{4}$ | no |  |
| $1 \overline{4}$ | 1, $\overline{2} \vee 3, \underline{4}$ | no | by Propagate ${ }^{+}$ |
| $1 \underline{4} \cdot \overline{2}$ | 1, $\overline{2} \vee 3, \overline{4}$ | no | by Decide |
| $1 \underline{4} \cdot \underline{2}$ | 1, $\overline{\underline{2}} \vee 3, \underline{\overline{4}}$ | $\overline{1} \vee 2 \vee 4$ | by $T$-Conflict |
| $1 \overline{4} \cdot \underline{2}$ | $1, \underline{\overline{2}} \vee 3, \overline{4}, \overline{1} \vee 2 \vee 4$ | $\overline{1} \vee 2 \vee 4$ | by Learn |
| 14 | $1, \overline{2} \vee 3, \overline{4}, \overline{1} \vee 2 \vee 4$ | no | by Restart |
| $1 \overline{4} 23$ | $1, \overline{2} \vee 3, \overline{4}, \overline{1} \vee 2 \vee 4$ | no | by Propagate ${ }^{+}$ |

## Modeling a Very Lazy Theory Approach

$$
\underbrace{g(a)=c}_{1} \wedge \underbrace{f(g(a)) \neq f(c)}_{\overline{2}} \vee \underbrace{g(a)=d}_{3} \wedge \underbrace{c \neq d}_{\overline{4}}
$$



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$$

| M | F | C | rule |
| :---: | :---: | :---: | :---: |
|  | 1, $\overline{2} \vee 3, \overline{\overline{4}}$ | no |  |
| $1 \overline{4}$ | $1, \overline{2} \vee 3, \underline{4}$ | no | by Propagate ${ }^{+}$ |
| $1 \overline{4} \cdot \overline{2}$ | 1, $\overline{2} \vee 3, \overline{4}$ | no | by Decide |
| $1 \overline{4} \cdot \overline{2}$ | $1, \overline{2} \vee 3, \overline{4}$ | $\overline{1} \vee 2 \vee 4$ | by $T$-Conflict |
| $1 \overline{4} \cdot \overline{2}$ | $1, \underline{2} \vee 3, \overline{4}, \overline{1} \vee 2 \vee 4$ | $\overline{1} \vee 2 \vee 4$ | by Learn |
| 14 | $1, \overline{2} \vee 3, \overline{4}, \overline{1} \vee 2 \vee 4$ | no | by Restart |
| $1 \overline{4} 23$ | $1, \frac{\overline{2}}{} \vee 3, \overline{4}, \overline{1} \vee 2 \vee 4$ | no | by Propagate ${ }^{+}$ |
| $\begin{array}{r} 1 \overline{4} 23 \\ \text { fail } \end{array}$ | $1, \overline{2} \vee 3, \overline{4}, \overline{1} \vee 2 \vee 4, \overline{1} \vee \overline{3} \vee 4$ | $\overline{1} \vee \overline{3} \vee 4$ | by $T$-Conflict, Learn by Fail |

## A Better Lazy Approach

The very lazy approach can be improved considerably with

- An on-line SAT engine, which can accept new input clauses on the fly


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- An on-line SAT engine, which can accept new input clauses on the fly
- an incremental and explicating $T$-solver, which can

1. check the $T$-satisfiability of M as it is extended and
2. identify a small $T$-unsatisfiable subset of M once M becomes $T$-unsatisfiable

## A Better Lazy Approach

$$
\underbrace{g(a)=c}_{1} \wedge \underbrace{f(g(a)) \neq f(c)}_{\overline{2}} \vee \underbrace{g(a)=d}_{3} \wedge \underbrace{c \neq d}_{\overline{4}}
$$

## A Better Lazy Approach

$$
\begin{gathered}
\underbrace{g(a)=c}_{1} \wedge \underbrace{f(g(a)) \neq f(c)}_{\overline{2}} \vee \underbrace{g(a)=d}_{3} \wedge \underbrace{c \neq d}_{\overline{4}} \\
\frac{\mathrm{M} \boldsymbol{\mathrm { F }} \quad \mathrm{C}, \overline{2} \vee 3, \overline{4} \quad \text { no } \quad \text { rule }}{}
\end{gathered}
$$

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## Lazy Approach - Strategies

Ignoring Restart (for simplicity), a common strategy is to apply the rules using the following priorities:

1. If a clause is falsified by the current assignment $M$, apply Conflict
2. If M is $T$-unsatisfiable, apply $T$-Conflict
3. Apply Fail or Explain+Learn+Backjump as appropriate
4. Apply Propagate
5. Apply Decide

## Lazy Approach - Strategies

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2. If M is $T$-unsatisfiable, apply $T$-Conflict
3. Apply Fail or Explain+Learn+Backjump as appropriate
4. Apply Propagate
5. Apply Decide

Note: Depending on the cost of checking the $T$-satisfiability of M ,
Step (2) can be applied with lower frequency or priority

## Theory Propagation

With $T$-Conflict as the only theory rule, the theory solver is used just to validate the choices of the SAT engine

[^0]
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With $T$-Conflict as the only theory rule, the theory solver is used just to validate the choices of the SAT engine

With $T$-Propagate and $T$-Explain, it can also be used to guide the engine's search [Tin02]

$$
\begin{aligned}
& T \text {-Propagate } \frac{l \in \operatorname{Lit}(\mathrm{~F}) \mathrm{M} \models_{T} l \quad l, \bar{l} \notin \mathrm{M}}{\mathrm{M}:=\mathrm{M} l} \\
& T \text {-Explain } \frac{\mathrm{C}=l \vee D \quad \bar{l}_{1}, \ldots, \bar{l}_{n} \models_{T} \bar{l} \quad \bar{l}_{1}, \ldots, \bar{l}_{n}<_{\mathrm{M}} \bar{l}}{\mathrm{C}:=l_{1} \vee \cdots \vee l_{n} \vee D}
\end{aligned}
$$

## Theory Propagation Example

$$
\underbrace{g(a)=c}_{1} \wedge \underbrace{f(g(a)) \neq f(c)}_{\overline{2}} \vee \underbrace{g(a)=d}_{3} \wedge \underbrace{c \neq d}_{\overline{4}}
$$

## Theory Propagation Example

$$
\begin{aligned}
& \underbrace{g(a)=c}_{1} \wedge \underbrace{f(g(a)) \neq f(c)}_{\overline{2}} \vee \underbrace{g(a)=d}_{3} \wedge \underbrace{c \neq d}_{\overline{4}} \\
& \frac{\mathrm{M} \quad \mathrm{~F} \quad \mathrm{C}}{1, \overline{2} \vee 3, \overline{4} \quad \text { no }}
\end{aligned}
$$

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$$
\begin{aligned}
& \underbrace{g(a)=c}_{1} \wedge \underbrace{f(g(a)) \neq f(c)}_{\overline{2}} \vee \underbrace{g(a)=d}_{3} \wedge \underbrace{c \neq d}_{\overline{4}}
\end{aligned}
$$

## Theory Propagation Example

## Theory Propagation Example



| M | F | C | rule |
| ---: | :--- | :--- | :--- |
|  | $1, \overline{2} \vee 3, \overline{4}$ | no |  |
| $1_{1} \overline{4} \overline{4}$ | $1, \overline{2} \vee 3, \overline{4}$ | no | by Propagate ${ }^{+}$ |
| $1 \frac{1}{4} \frac{2}{2} \overline{3}$ | $1, \overline{2} \vee 3, \overline{4}$ | no | by $T$-Propagate $\left(1 \models_{T} 2\right)$ |
| 142 | $1, \overline{2} \vee 3, \overline{4}$ | no | by $T$-Propagate $\left(1, \overline{4}=_{T}\right)$ |
| fail | $1, \overline{2} \vee 3, \overline{4}$ | $\overline{2} \vee 3$ | by Conflict |

Note: $T$-propagation eliminates search altogether in this case no applications of Decide are needed

## Modeling Modern Lazy SMT Solvers

At the core, current lazy SMT solvers are implementations of the transition system with rules
(1) Propagate, Decide, Conflict, Explain, Backjump, Fail
(2) $T$-Conflict, $T$-Propagate, $T$-Explain
(3) Learn, Forget, Restart

## Reasoning by Cases in Theory Solvers

For certain theories, determining that a set $M$ is $T$-unsatisfiable requires reasoning by cases.

Example: $T=$ the theory of arrays.

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M=\{\underbrace{r(w(a, i, x), j) \neq x}_{1}, \underbrace{r(w(a, i, x), j) \neq r(a, j)}_{2}\}
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$$

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$i \neq j)$ Then, $r(w(a, i, x), j)=r(a, j)$. Contradiction with 2.

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Example: $T=$ the theory of arrays.

$$
M=\{\underbrace{r(w(a, i, x), j) \neq x}_{1}, \underbrace{r(w(a, i, x), j) \neq r(a, j)}_{2}\}
$$

$i=j)$ Then, $r(w(a, i, x), j)=x$. Contradiction with 1 .
$i \neq j)$ Then, $r(w(a, i, x), j)=r(a, j)$. Contradiction with 2.

Conclusion: $M$ is $T$-unsatisfiable

## Case Splitting

A complete $T$-solver reasons by cases via (internal) case splitting and backtracking mechanisms

Basic idea: encode case splits as sets of clauses and send them as needed to the SAT engine for it to split on them [BNOT06]

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Possible benefits:

- All case-spititing is coordinated by the SAT engine
- Only have to implement case-splitting infrastructure in one place



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## Splitting on Demand

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## Basic Scenario:

$$
\mathrm{M}=\{\ldots, s=\underbrace{r(w(a, i, t), j)}_{s^{\prime}}, \ldots\}
$$

- Main SMT module: "Is M T-unsatisfiable?"
'I do not know yet, but it will help me if you consider


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$$
\mathrm{M}=\{\ldots, s=\underbrace{r(w(a, i, t), j)}_{s^{\prime}}, \ldots\}
$$

- Main SMT module: "Is M T-unsatisfiable?"
- $T$-solver: "I do not know yet, but it will help me if you consider these theory lemmas:

$$
s=s^{\prime} \wedge i=j \rightarrow s=t, \quad s=s^{\prime} \wedge i \neq j \rightarrow s=r(a, j) "
$$

## Modeling Splitting on Demand

To model the generation of theory lemmas for case splits, add the rule
$T$-Learn

$$
\frac{\models_{T} \exists \mathbf{v}\left(l_{1} \vee \cdots \vee l_{n}\right) \quad l_{1}, \ldots, l_{n} \in L_{\mathrm{S}} \quad \mathbf{v} \text { vars not in } \mathrm{F}}{\mathrm{~F}:=\mathrm{F} \cup\left\{l_{1} \vee \cdots \vee l_{n}\right\}}
$$

where $L_{\mathrm{S}}$ is a finite set of literals dependent on the initial set of clauses (see [BNOT06] for a formal definition of $L_{\mathrm{S}}$ )

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$$
\frac{\models_{T} \exists \mathbf{v}\left(l_{1} \vee \cdots \vee l_{n}\right) \quad l_{1}, \ldots, l_{n} \in L_{\mathrm{S}} \quad \mathbf{v} \text { vars not in } \mathrm{F}}{\mathrm{~F}:=\mathrm{F} \cup\left\{l_{1} \vee \cdots \vee l_{n}\right\}}
$$

where $L_{\mathrm{S}}$ is a finite set of literals dependent on the initial set of clauses (see [BNOT06] for a formal definition of $L_{\mathrm{S}}$ )

Note: For many theories with a theory solver, there exists an appropriate finite $L_{\mathrm{S}}$ for every input $F$
The set $L_{\mathrm{S}}$ does not need to be computed explicitly

## Modeling Splitting on Demand

Now we can relax the requirement on the theory solver:
When $\mathrm{M} \models_{\mathrm{p}} \mathrm{F}$, it must either

- determine whether $\mathrm{M} \models_{T} \perp$ or
- generate a new clause by T-Learn containing at least one literal of $L_{\mathrm{S}}$ undefined in M


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The $T$-solver is required to determine whether $\mathrm{M} \models_{T} \perp$ only if all literals in $L_{\mathrm{S}}$ are defined in M

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The $T$-solver is required to determine whether $\mathrm{M} \models_{T} \perp$ only if all literals in $L_{\mathrm{S}}$ are defined in M

Note: In practice, to determine if $\mathrm{M} \models_{T} \perp$, the $T$-solver only needs a small subset of $L_{\mathrm{S}}$ to be defined in M

## Example - Theory of Finite Sets

$$
F: x=y \cup z \wedge y \neq \varnothing \vee x \neq z
$$

| M | F | rule |
| ---: | :--- | :--- | :--- |
| $x=y \cup z$ | $F$ | by Propagate $^{+}$ |

## Example - Theory of Finite Sets

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| M | F | rule |
| ---: | :--- | :--- | :--- |
| $x=y \cup z \bullet y=\varnothing$ | $F$ | by Propagate ${ }^{+}$ |
| $x=y$ | by Decide |  |

## Example - Theory of Finite Sets



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-solver can make the following deductions at this point:

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This enables an application of $T$-Conflict with clause

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## Example - Theory of Finite Sets


$T$-solver can make the following deductions at this point:

$$
e \in x \cdots \quad \Rightarrow \quad \Rightarrow \quad \Rightarrow \quad \operatorname{l}, \vec{y} \cup z \cdots e \in \varnothing \Rightarrow \perp
$$

This enables an application of $T$-Conflict with clause

$$
x \neq y \cup z \vee y \neq \varnothing \vee x=z \vee e \notin x \vee e \in z
$$

## Applications

## Some Applications of SMT

## Program Analysis and Verification

- Software Model Checking ${ }^{1}$ (e.g., BLAST, SLAM)
- K-Induction-Based Model Checking ${ }^{2}$ (e.g., Kind)
- Concolic or Directed Automated Random Testing ${ }^{3}$ (e.g., CUTE, KLEE, PEX)
- Program Verifiers (e.g., VCC, ${ }^{4}$ Why3 ${ }^{5}$ )
- Translation Validation for Compilers (e.g., TVOC ${ }^{6}$ )

[^1]
## Some Applications of SMT

Non-verification Applications

- AI (e.g., Robot Task Planning ${ }^{7}$ )
- Biology (e.g., Analysis of Synthetic Biology Models ${ }^{8}$ )
- Databases (e.g., Checking Preservation of Database Integrity ${ }^{9}$ )
- Network Analysis (e.g., Checking Security of OpenFlow Rules ${ }^{10}$ )
- Scheduling (e.g., Rotating Workforce Scheduling ${ }^{11}$ )
- Security (e.g., Automatic Exploit Generation ${ }^{12}$ )
- Synthesis (e.g., Symbolic Term Exploration ${ }^{13}$ )

[^2]
## New Theories

SMT users are clamouring for more capabilities
New theories in the pipeline

- Theory of sequences
- Theory of finite fields
- Theory of bags and tables


## Going forward

- There is a huge opportunity to design and implement decision procedures for new domain-specific theories


## Scalability

Plenty of room for performance improvements

- SMT innovations continue at both the system and algorithm level
- Example: Each year at SMT-COMP, new problems are solved that were previously too difficult for any solver
- Parallel computing still largely untapped

Amazon

- Ongoing collaboration with Amazon with ambitious goals for providing SMT solving as a service in the cloud
- Lots of interesting research questions about how to make use of Amazon's massive resources to do SMT solving on a massive scale


## Summary

## SMT solvers

- Provide general-purpose logical reasoning
- Can be customized for domain-specific reasoning
- Enabler for formal methods: automatic, expressive, scalable
- No shortage of challenging research problems
- with immediate practical impact


## More information

SMT resources

- SMT Survey Article: available at

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http://theory.stanford.edu/~barrett/pubs/BKM14.pdf
```

- SMT-LIB standards and library http://smt-lib.org
- SMT Competition http://smtcomp.org
- SMT Workshop http://smt-workshop.org
cvc5
- Visit the cvc5 website: http://cvc5.github.io
- Contact a cve5 team member
- We welcome questions, feedback, collaboration proposals


## Suggested Readings

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